

```

RECURSIVE SUBROUTINE FM_INTEGRATE(F,N,A,B,TOL,RESULT,KPRT,NW)
USE FMVALS
USE FMZM
IMPLICIT NONE

```

! High-precision numerical integration.

! Integrate F(X,N) from A to B. N is passed on to function F to indicate which function to use in cases where several different functions may be defined there.

! WARNING: If the function F being integrated or one of its derivatives does not exist at one or both of the endpoints (A,B), the endpoints should be exactly representable in FM's number system. For non-exact numbers like 1/3, sqrt(2), or pi/2, when FM_INTEGRATE raises precision to evaluate the integration formula the endpoints are not accurate enough at the higher precision.

! Example: Integrate sqrt(tan(x)) from 0 to pi/2.
! First, pi/2 is not exact as an FM number. At some precisions it may have rounded up, making tan(x) negative and causing an error in sqrt. Using sqrt(abs(tan(x))) is safer.
! Second, b = pi/2 has been computed at the user's precision, so when FM_INTEGRATE raises precision, the value of b is just zero-padded on the end, which does not give enough information about how f(x) behaves near the singularity at pi/2.

! Make the endpoints exact by changing variables. Change the interval to [0 , 1]:

! so

$$u = (2/\pi) * x \Rightarrow du = (2/\pi) * dx$$

! new limits

$$x = (\pi/2) * u \Rightarrow dx = (\pi/2) * du$$

$$x = 0 \Rightarrow u = 0 \text{ and } x = \pi/2 \Rightarrow u = 1$$

! New integral: Integrate (pi/2) * sqrt(abs(tan(pi*u/2))) from 0 to 1.

! Now the function F should declare a local saved type(fm) variable PI, and then use CALL FM_PI(PI) each time F is called to make sure the value of PI is correct at the higher precision being used by FM_INTEGRATE when F is called.

```

TYPE (FM) :: A,B,RESULT,TOL
TYPE (FM), EXTERNAL :: F
INTEGER :: N,KPRT,NW
INTENT (IN) :: N,A,B,TOL,KPRT,NW
INTENT (INOUT) :: RESULT

```

! A,B,TOL, and RESULT are all type (FM) variables, and function F returns a type (FM) result.

! RESULT is returned as the value of the integral, with ABS((RESULT-true)/true) less than TOL (i.e., TOL is a relative error tolerance).
! For example, to get 30 significant digits correct for the integral, set TOL = 1.0E-30.

! FM precision must be set high enough in the calling program (using FM_SET) so that 1+TOL > 1 at that precision. Using TOL = EPSILON(TO_FM(1)) will usually get a full precision result, but for some functions this might fail. A better strategy is to set precision higher than the accuracy required for the integral. For example, to get the integral to 50 significant

! digits, CALL FMSET(60) and then set TOL = TO_FM(' 1.0E-50 ') before the call to FM_INTEGRATE.

! KPRT can be used to show intermediate results on unit NW.
! KPRT = 0 for no output
! = 1 prints a summary for each call to FM_INTEGRATE
! = 2 prints a trace of all iterations.

! NW is the unit number used for KPRT output and any error or warning messages.

! No method for numerical integration is foolproof. Since it samples only a finite number of
! function values, any numerical integration algorithm can be made to fail by choosing a
! sufficiently badly-behaved function. Such functions often vary by many orders of magnitude
! over relatively small fractions of the interval (A,B).

! F should be well-behaved in the interior of the interval (A,B).
! The routine tries to handle any singularities of F or F' at A and/or B, so cases with interior
! singularities should be done as separate calls having the singularities as endpoints.
! The routine will try to handle cases where F or F' has singularities inside (A,B), but then
! the time will be much slower and the routine might fail.

! For a function with a removable singularity in the interior of the interval, such as
! $f(x) = 1/\ln(x) - 1/(x-1)$, define F(X,N) to check for $X = 1$ and return the correct limiting
! value, 0.5 in this case, when X is 1.

! Among functions with no singularities, examples of badly behaved functions are those with one
! or more extremely narrow tall spikes in their graphs. If possible, identify the peaks of any
! such spikes first, then make separate calls with the peaks as endpoints of the intervals of
! integration.

! If the value of the integral is zero or very close to zero, relative error may be undefined, so
! this routine may fail to converge and then return unknown. For these cases, try breaking the
! integral into two pieces and calling twice to get two non-zero results. These two results can
! then be added, often giving the original integral with sufficiently small absolute error even
! though small relative error could not be attained.

! If the function values are too extreme, it can cause problems. For example, if an exponential
! in F underflows and then is multiplied by something bigger than one, then F will return unknown.
! If the result of the integral is much larger than the underflow threshold (TINY(TO_FM(1))), then
! it is safe to set the underflowed results in F to zero to avoid getting unknown.

! If the function is nearly divergent FM_INTEGRATE may fail. $1/x$ from 0 to b is divergent.
! $1/x^{0.99}$ converges, but so slowly that FM_INTEGRATE may run a long time and then might fail.
! $1/x^{0.9999}$ converges even more slowly and FM_INTEGRATE may fail by declaring that the integral
! seems divergent.

! When the integrand is highly (or infinitely) oscillatory, FM_INTEGRATE may fail.
! If F has more than about 100 oscillations on the interval (A,B), it may be necessary to break
! the interval into smaller intervals and call FM_INTEGRATE several times.
! For infinitely many oscillations, like $\sin(1/x)$ from 0 to 1, first turn the integral into an
! infinite series by calling FM_INTEGRATE to integrate each separate loop between roots of
! $\sin(1/x)$. The function is well-behaved for each call, so FM_INTEGRATE can get high precision
! quickly for each. Next form a sequence of k partial sums for this series. The series converges
! slowly, with 50 or 100 terms giving only 3 or 4 significant digits of the sum, so an
! extrapolation method can be used to get a more accurate value of the sum of this series from
! its first k terms. For an alternating series like this, the extrapolation method of Cohen,
! Villegas, and Zagier often works very well.

```
! Repeated Aitken extrapolation could be used instead -- it is a more widely known method.
! Sample program Oscillate.f95 computes this integral.
```

```
! M is the maximum level for the integration algorithm. The number of function
! evaluations roughly doubles for each successive level until the tolerance is met.
! Using M = 12 allows up to about 5,000 digits for most integrals, but the upper
! limit for a given M depends on the function.
! Raising M further will approximately double the maximum precision for each
! extra level, but will also double the memory usage for each extra level.
```

```
INTEGER, PARAMETER :: M = 12
INTEGER, PARAMETER :: NT = 20*2**M
TYPE (FM), SAVE :: ST_SAVE(0:NT)
INTEGER, SAVE :: PRECISION_OF(0:NT) = 0
INTEGER :: ABSIGN,I,ISTEP,K,KWSAVE,NDS,NDSAVE,NRETRY,NUMBER_USED_SAVE
INTEGER, SAVE :: R_LEVEL = 0, NUM_F = 0
```

```
! Local TYPE (FM) variables can be tricky in recursive routines. If they are declared
! with the SAVE attribute and initialized as usual, they will be shared among
! all levels of the recursive calls. Here we need them to be different for each level
! of recursion, so we initialize them with index -2 and do not make them saved.
! To avoid leaking memory, we also save and restore NUMBER_USED in the same way as the
! low-level routines in FM.
```

```
TYPE (FM) :: A1,AB2,B1,C1,C2,CI,CT,D,EPS,ERR1,ERR2,FMAX,FMAX2,H,HF, LAST_H,PI,PRIOR_HS, &
S,S1,S2,SI,ST,T,TOL1,TOL2,X,XF,XMAX,V,W
```

```
CHARACTER(80) :: ST1,ST2
REAL :: TIME1,TIME2
LOGICAL :: SPIKE_FOUND,ST_IS_SAVED
```

```
CALL FM_ENTER_USER_ROUTINE
```

```
! Initialize the index values for the local FM variables.
! This cannot be done in the TYPE statement above, or with a DATA statement, because
! those forms of initialization force the SAVE attribute to be applied to the variables.
```

```
CALL FM_INT_INIT(A1,AB2,B1,C1,C2,CI,CT,D,EPS,ERR1,ERR2,FMAX,FMAX2,H,HF, LAST_H,PI,PRIOR_HS, &
S,S1,S2,SI,ST,T,TOL1,TOL2,X,XF,XMAX,V,W)
```

```
! Iterative tanh-sinh integration is used, increasing the order until convergence
! is obtained, or M levels have been done.
```

```
TEMPV_CALL_STACK = TEMPV_CALL_STACK + 1
RESULT = 0
NUMBER_USED_SAVE = NUMBER_USED
```

```
NCALL = NCALL + 1
NAMEST(NCALL) = 'INTEGRATE'
KWSAVE = KW
KW = NW
R_LEVEL = R_LEVEL + 1
NRETRY = 0
IF (KPRT >= 2) THEN
  WRITE (NW, "(A)") ' '
```

```

WRITE (NW,"(A,I9,A)") ' Input to FM_INTEGRATE.    Function N = ',N,'.    A, B ='
CALL FM_PRINT(A)
CALL FM_PRINT(B)
CALL FM_FORM('ES20.8',TOL,ST1)
WRITE (NW,"(A,A)") ' TOL =',TRIM(ST1)
ENDIF
CALL CPU_TIME(TIME1)

```

! Check for special cases.

```

IF (A == B) THEN
  A1 = F(A,N)
  IF (R_LEVEL <= 1) THEN
    NUM_F = 1
  ELSE
    NUM_F = NUM_F + 1
  ENDIF
  IF (MWK(START(A1%MF)+2) == MUNKNO) THEN
    CALL FM_F_FAIL(A,N,NW)
    PRIOR_HS = A1
    GO TO 120
  ELSE
    PRIOR_HS = 0
    GO TO 120
  ENDIF
ENDIF
ENDIF

```

! Check to make sure the user has set precision high enough for the value of TOL chosen.

```

TOL1 = TOL
IF (TOL < ABS(EPSILON(A))) THEN
  WRITE (NW,"(A)") ' '
  WRITE (NW,"(A)") ' Error in FM_INTEGRATE.  TOL is '
  CALL FM_PRINT(TOL)
  WRITE (NW,"(A)") ' This is too small for the current precision level.  Current epsilon ='
  TOL1 = ABS(EPSILON(A))
  CALL FM_PRINT(TOL1)
  WRITE (NW,"(A)") ' This larger value will be used.  TOL ='
  CALL FM_PRINT(TOL1)
  WRITE (NW,"(A)") ' Use FM_SET to set a higher precision before the call to'
  WRITE (NW,"(A)") ' FM_INTEGRATE if the smaller TOL is needed.'
ENDIF

```

! Raise the precision.

! Check for an integrable singularity at either endpoint, and increase precision
! if it seems that a retry would be needed at the first precision.

```

NDSAVE = NDIG
A1 = LOG10(F(A+(B-A)*TO_FM(' 1.0E-10 '),N)/F(A+(B-A)*TO_FM(' 1.0E-20 '),N))/10
B1 = LOG10(F(B-(B-A)*TO_FM(' 1.0E-10 '),N)/F(B-(B-A)*TO_FM(' 1.0E-20 '),N))/10
IF (R_LEVEL <= 1) THEN
  NUM_F = 4
ELSE
  NUM_F = NUM_F + 4
ENDIF
IF (A1 < -0.999 .OR. B1 < -0.999) THEN

```

```

PRIOR_HS = TO_FM(' UNKNOWN ')
WRITE (NW,"(A)") ' '
WRITE (NW,"(A,I9,A)") ' FM_INTEGRATE failed -- F(X,N) for N = ',N, &
' seems to have a non-integrable singularity'
WRITE (NW,"(A)") ' at an endpoint. A,B ='
CALL FM_PRINT(A)
CALL FM_PRINT(B)
WRITE (NW,"(A)") ' Check the limits of integration, function number (N), and' // &
' function definition.'
WRITE (NW,"(A)") ' '
GO TO 120

```

```

ENDIF
NDIG = NDIG+INT(30/ALOGMT)
CALL FM_EQU_R1(A1,NDSAVE,NDIG)
CALL FM_EQU_R1(B1,NDSAVE,NDIG)
IF (A1 < -0.2 .OR. B1 < -0.2) NDIG = 2*NDIG

CALL CPU_TIME(TIME1)

```

! Start here when doing a retry.

```

110 NRETRY = NRETRY + 1
CALL FM_EQU(A,A1,NDSAVE,NDIG)
CALL FM_EQU(B,B1,NDSAVE,NDIG)
ABSIGN = 1
IF (A1 > B1) THEN
    CALL FM_EQU(B,A1,NDSAVE,NDIG)
    CALL FM_EQU(A,B1,NDSAVE,NDIG)
    ABSIGN = -1
ELSE IF (A1 == B1) THEN
    PRIOR_HS = 0
    GO TO 120
ENDIF
CALL FM_EQU(TOL1,TOL2,NDSAVE,NDIG)

IF (KPRT >= 2) THEN
    WRITE (NW,"(A)") ' '
    WRITE (NW,"(A,I9,A,I5)") ' Begin FM_INTEGRATE. NDIG = ',NDIG,' Recursion level = ', &
R_LEVEL
ENDIF

S = 0
PRIOR_HS = 0
ERR2 = 1
EPS = EPSILON(TOL2)
D = ABS(B1-A1)/100
FMAX = 0
FMAX2 = 0
XMAX = A1
H = 1
LAST_H = H/2**M
CALL FM_PI(PI)

HF = (B1-A1)/2
AB2 = A1 + HF
DO K = 1, M

```

```

H = H/2
ISTEP = 2**(M-K)
IF (K > 1) THEN
  T = ISTEP*LAST_H
  CALL FM_CHSH(T,C1,S1)
  T = 2*S1*C1
  C2 = C1**2 + S1**2
  S2 = T
ENDIF
DO I = 0, NT, ISTEP
  IF (MOD(I,2*ISTEP) /= 0 .OR. K == 1) THEN

```

! The + or -X values are the abscissas for interval (-1,1).
! XF translates these to the interval (A,B).

```

IF (I == 0) THEN
  X = 0
  W = PI/2
  XF = HF*X + AB2
  T = F(XF,N)
  NUM_F = NUM_F + 1
  IF (MWK(START(T%MFM)+2) == MUNKNO) THEN
    CALL FM_F_FAIL(XF,N,NW)
    PRIOR_HS = T
    GO TO 120
  ENDIF
  FMAX2 = MAX(FMAX2,ABS(T))
  IF (ABS(T) > FMAX .AND. XF > A1+D .AND. XF < B1-D) THEN
    FMAX = ABS(T)
    XMAX = XF
  ENDIF
  S = S + W*HF*T
ELSE
  IF (K == 1) THEN
    T = I*LAST_H
    CALL FM_CHSH(T,CI,SI)
  ELSE

```

! Use the hyperbolic addition formulas to get the next cosh and sinh
! quickly when evaluated at I*LAST_H.

```

IF (I == ISTEP) THEN
  CI = C1
  SI = S1
ELSE
  T = SI*C2 + CI*S2
  CI = CI*C2 + SI*S2
  SI = T
  C1 = CI
  S1 = SI
ENDIF
ENDIF
ST_IS_SAVED = .FALSE.
IF (ST_SAVE(I)%MFM > 0) THEN
  IF (PRECISION_OF(I) >= NDIG) ST_IS_SAVED = .TRUE.
ENDIF

```

```

IF (ST_IS_SAVED) THEN
  ST = ST_SAVE(I)
  CT = SQRT(1+ST**2)
ELSE
  T = PI*SI/2
  CALL FM_CHSH(T,CT,ST)
  ST_SAVE(I) = ST
  PRECISION_OF(I) = NDIG
ENDIF
W = (PI/2)*CI/CT**2
IF (W < EPS) EXIT
X = ST/CT
XF = HF*(-X) + AB2
IF (XF > A1) THEN
  T = F(XF,N)
  NUM_F = NUM_F + 1
  IF (MWK(START(T%MFM)+2) == MUNKNO) THEN
    CALL FM_F_FAIL(XF,N,NW)
    PRIOR_HS = T
    GO TO 120
  ENDIF
  FMAX2 = MAX(FMAX2,ABS(T))
  IF (ABS(T) > FMAX .AND. XF > A1+D .AND. XF < B1-D) THEN
    FMAX = ABS(T)
    XMAX = XF
  ENDIF
  S = S + W*HF*T
ENDIF
XF = HF*(X) + AB2
IF (XF < B1) THEN
  T = F(XF,N)
  NUM_F = NUM_F + 1
  IF (MWK(START(T%MFM)+2) == MUNKNO) THEN
    CALL FM_F_FAIL(XF,N,NW)
    PRIOR_HS = T
    GO TO 120
  ENDIF
  FMAX2 = MAX(FMAX2,ABS(T))
  IF (ABS(T) > FMAX .AND. XF > A1+D .AND. XF < B1-D) THEN
    FMAX = ABS(T)
    XMAX = XF
  ENDIF
  S = S + W*HF*T
ENDIF
ENDIF
ENDIF
ENDIF
ENDDO
IF (KPRT >= 2) THEN
  WRITE (NW,"(A)" ' '
  WRITE (NW,"(A,I9,A,I9,A)") ' K = ',K,' ',NUM_F, &
  ' function calls so far. Integral approximation ='
  V = H*S
  CALL FM_PRINT(V)
ENDIF
IF (K > 1) THEN
  ERR1 = ERR2

```

```

IF (S /= 0) THEN
  ERR2 = ABS( (PRIOR_HS - H*S)/(H*S) )
ELSE
  ERR2 = ABS( (PRIOR_HS - H*S) )
ENDIF
IF (KPRT >= 2) THEN
  CALL FM_FORM('ES15.3',ERR2,ST1)
  WRITE (NW,"(A,A)") '          relative error of the last two approximations = ', &
    TRIM(ST1)
ENDIF

```

! Check for convergence.

```

IF (K > 3 .AND. ERR2 > 0 .AND. ERR2 < TOL2/10.0) EXIT
IF (K > 5 .AND. ERR2 == 0) EXIT

```

! If the errors do not decrease fast enough, raise precision and try again.

```

IF (K > 3*NRETRY .AND. ERR1 > 0 .AND. ERR2 > 0) THEN
  IF (LOG(ERR2)/LOG(ERR1) < 1.2 .AND. ERR1 < 1.0D-6) THEN
    NDIG = 2*NDIG
    IF (KPRT >= 2) THEN
      WRITE (NW,"(A,I9,A,I9)") ' FM_INTEGRATE Retry. So far, NUM_F = ',NUM_F, &
        ' New NDIG = ',NDIG
    ENDIF
    IF (NRETRY <= 3) GO TO 110
    NDIG = NDIG/2
  ENDIF
ENDIF
ENDIF
ENDIF
PRIOR_HS = H*S

```

! No convergence in M iterations.

! Before giving up, look for an interior singularity or tall spike. If one is found,
! split (A,B) into two intervals with the interior singularity as an endpoint, and try
! again as two integrals.

```

IF (K == M .OR. (K >= 9 .AND. ERR2 > 1.0D-7 .AND. ABS(TOL2) < 1.0D-16)) THEN
  IF (KPRT >= 2) THEN
    WRITE (NW,"(A)") ' '
    WRITE (NW,"(A,I6,A)") ' No convergence in ',M, &
      ' iterations. Look for an interior singularity.'
    CALL FM_FORM('ES25.6',XMAX,ST1)
    CALL FM_FORM('ES25.6',FMAX,ST2)
    WRITE (NW,"(I9,A,A,A)") NUM_F,' function calls so far. XMAX, FMAX =', &
      TRIM(ST1),TRIM(ST2)
  ENDIF
  CALL FM_SPIKE(F,N,A1,B1,XMAX,FMAX,NUM_F,SPIKE_FOUND,KPRT,NW)
  CALL FMEQU_R1(A1%MF,M,NDIG,NDSAVE)
  CALL FMEQU_R1(B1%MF,M,NDIG,NDSAVE)
  CALL FMEQU_R1(XMAX%MF,M,NDIG,NDSAVE)
  NDS = NDIG
  NDIG = NDSAVE
  IF (SPIKE_FOUND) THEN
    IF (MIN(ABS(A-XMAX),ABS(B-XMAX)) < 1.01*D) THEN
      NDIG = 2*NDS
    ENDIF
  ENDIF
ENDIF

```



```

        IF (NRETRY <= 5) GO TO 110
        NDIG = NDSAVE
    ENDF
    IF (KPRT >= 2) THEN
        WRITE (NW,"(A)") ' '
        WRITE (NW,"(A)") ' Split the integral. First half: A,B = '
        CALL FM_PRINT(A1)
        CALL FM_PRINT(XMAX)
    ENDF
    CALL FM_INTEGRATE(F,N,A1,XMAX,TOL,C1,KPRT,NW)
    IF (MWK(START(C1%MF)+2) == MUNKNO) THEN
        PRIOR_HS = C1
        GO TO 120
    ENDF
    IF (KPRT >= 2) THEN
        WRITE (NW,"(A)") ' '
        WRITE (NW,"(A)") ' Split the integral. Second half: A,B = '
        CALL FM_PRINT(XMAX)
        CALL FM_PRINT(B1)
    ENDF
    CALL FM_INTEGRATE(F,N,XMAX,B1,TOL,C2,KPRT,NW)
    PRIOR_HS = C1 + C2
    GO TO 120
    ENDF
    CALL FM_INT_FAIL(N,A,B,TOL,M,ERR2,PRIOR_HS,NW)
    PRIOR_HS = TO_FM(' UNKNOWN ')
    GO TO 120
    ENDF
ENDDO

PRIOR_HS = ABSIGN*H*S

!           Round the result and return.

120 CALL FM_EQU(PRIOR_HS,RESULT,NDIG,NDSAVE)

NDIG = NDSAVE
NCALL = NCALL - 1
CALL CPU_TIME(TIME2)

IF (KPRT >= 2 .OR. ( R_LEVEL <= 1 .AND. KPRT == 1 ) ) THEN
    WRITE (NW,"(A)") ' '
    WRITE (NW,"(A,I9,A)") ' Return from FM_INTEGRATE. Function N = ',N,', A, B ='
    CALL FM_PRINT(A)
    CALL FM_PRINT(B)
    CALL FM_FORM('ES20.8',TOL,ST1)
    WRITE (NW,"(A,A)") ' TOL =',TRIM(ST1)
    IF (ABS(TIME2-TIME1) > 0.0001 .AND. ABS(TIME2-TIME1) < 1000.0) THEN
        WRITE (NW,"(1X,I9,A,F9.5,A)") NUM_F,' function calls were made in ',TIME2-TIME1, &
            ' seconds.'
        WRITE (NW,"(A)") ' RESULT ='
    ELSE
        WRITE (NW,"(1X,I9,A,ES14.5,A)") NUM_F,' function calls were made in ',TIME2-TIME1, &
            ' seconds.'
        WRITE (NW,"(A)") ' RESULT ='
    ENDF

```

```

    CALL FM_PRINT(RESULT)
ENDIF
KW = KWSAVE
R_LEVEL = R_LEVEL - 1
TEMPV_CALL_STACK = TEMPV_CALL_STACK - 1
NUMBER_USED = NUMBER_USED_SAVE

CALL FM_EXIT_USER_ROUTINE
END SUBROUTINE FM_INTEGRATE

SUBROUTINE FM_INT_INIT(A1,AB2,B1,C1,C2,CI,CT,D,EPS,ERR1,ERR2,FMAX,FMAX2,H,HF, LAST_H,PI, &
                    PRIOR_HS,S,S1,S2,SI,ST,T,TOL1,TOL2,X,XF,XMAX,V,W)

USE FMZM
IMPLICIT NONE
TYPE (FM) :: A1,AB2,B1,C1,C2,CI,CT,D,EPS,ERR1,ERR2,FMAX,FMAX2,H,HF, LAST_H,PI,PRIOR_HS, &
            S,S1,S2,SI,ST,T,TOL1,TOL2,X,XF,XMAX,V,W
CALL FM_ENTER_USER_ROUTINE
A1%MFM = -2
AB2%MFM = -2
B1%MFM = -2
C1%MFM = -2
C2%MFM = -2
CI%MFM = -2
CT%MFM = -2
D%MFM = -2
EPS%MFM = -2
ERR1%MFM = -2
ERR2%MFM = -2
FMAX%MFM = -2
FMAX2%MFM = -2
H%MFM = -2
HF%MFM = -2
LAST_H%MFM = -2
PI%MFM = -2
PRIOR_HS%MFM = -2
S%MFM = -2
S1%MFM = -2
S2%MFM = -2
SI%MFM = -2
ST%MFM = -2
T%MFM = -2
TOL1%MFM = -2
TOL2%MFM = -2
X%MFM = -2
XF%MFM = -2
XMAX%MFM = -2
V%MFM = -2
W%MFM = -2
CALL FM_EXIT_USER_ROUTINE
END SUBROUTINE FM_INT_INIT

SUBROUTINE FM_INT_FAIL(N,A,B,TOL,M,ERR,VAL,NW)
USE FMZM
IMPLICIT NONE
INTEGER :: N,M,NW
TYPE (FM) :: A,B,TOL,ERR,VAL

```

```

CALL FM_ENTER_USER_ROUTINE
WRITE (NW,*) ' '
WRITE (NW,*) ' FM_INTEGRATE failed -- no convergence in ',M,' iterations.'
WRITE (NW,*) ' UNKNOWN has been returned in RESULT.'
WRITE (NW,*) ' Possible causes: (1) highly oscillatory integrand'
WRITE (NW,*) '                (2) non-convergent integral'
WRITE (NW,*) '                (3) integrable singularity in the interior of interval (A,B)'
WRITE (NW,*) '                (4) narrow spike in the interior of interval (A,B)'
WRITE (NW,*) '                (5) integral too close to zero'
WRITE (NW,*) ' A possible remedy for the last 3 is to split the integral into two pieces,'
WRITE (NW,*) ' making two calls to FM_INTEGRATE and then adding the two results.'
WRITE (NW,*) ' Put singularities or spikes at the endpoints of the intervals of integration.'
WRITE (NW,*) ' '
WRITE (NW,*) ' Function N = ',N,'.    A, B ='
CALL FM_PRINT(A)
CALL FM_PRINT(B)
WRITE (NW,*) ' TOL ='
CALL FM_PRINT(TOL)
WRITE (NW,*) ' The last integral approximation ='
CALL FM_PRINT(VAL)
WRITE (NW,*) ' The estimated relative error in the last integral approximation ='
CALL FM_PRINT(ERR)
WRITE (NW,*) ' '

```

```

CALL FM_EXIT_USER_ROUTINE
END SUBROUTINE FM_INT_FAIL

```

```

SUBROUTINE FM_F_FAIL(X,N,NW)
USE FMZM
IMPLICIT NONE
INTEGER :: N,NW
TYPE (FM) :: X

```

```

CALL FM_ENTER_USER_ROUTINE
WRITE (NW,*) ' '
WRITE (NW,*) ' FM_INTEGRATE failed -- F(X,N) gave UNKNOWN for N = ',N,' and X ='
CALL FM_PRINT(X)
WRITE (NW,*) ' Check the limits of integration, function number (N), and' // &
' function definition.'
WRITE (NW,*) ' Be careful of rounding at an irrational endpoint producing an' // &
' illegal function argument.'
WRITE (NW,*) ' Example: Integrate log( cos( t ) ) from 0 to pi/2'
WRITE (NW,*) ' At some precisions the computed value of pi/2 rounds up, giving' // &
' a small negative cos(t),'
WRITE (NW,*) ' which then causes the log function to return UNKNOWN.'
WRITE (NW,*) ' Possible fixes:'
WRITE (NW,*) '     Change variables to get an integral from 0 to 1'
WRITE (NW,*) '     Change the function to log( abs( cos( t ) ) )'
WRITE (NW,*) '     Compute pi/2 with rounding toward -infinity'
WRITE (NW,*) ' '

```

```

CALL FM_EXIT_USER_ROUTINE
END SUBROUTINE FM_F_FAIL

```

```

SUBROUTINE FM_SPIKE(F,N,A,B,XMAX,FMAX,NUM_F,SPIKE_FOUND,KPRT,NW)

```

```
USE FMVALS
USE FMZM
IMPLICIT NONE
```

```
! look for an interior singularity or tall spike in F(X,N).
! After getting no convergence in M iterations in FM_INTEGRATE, FMAX = ABS(F(XMAX,N)) was
! the largest magnitude found for F on the interval (A+D,B-D), where D = ABS(B-A)/100.
```

```
TYPE (FM) :: A,B,XMAX,FMAX
TYPE (FM), EXTERNAL :: F
INTEGER :: N,NUM_F,KPRT,NW
LOGICAL :: SPIKE_FOUND
TYPE (FM), SAVE :: AB,AVERAGE,D,DX,FPMAX,EPS,F1,F2,H,T,X1,XPMAX
INTEGER :: J
```

```
CALL FM_ENTER_USER_ROUTINE
SPIKE_FOUND = .FALSE.
IF (KPRT >= 2) THEN
  WRITE (NW,"(A)") ' Enter FM_SPIKE'
ENDIF
```

```
DX = ABS(B-A)/100
H = MIN(XMAX-A,B-XMAX)/2
```

```
AVERAGE = 0
DO J = 1, 99
  X1 = A + (J*(B-A))/100
  F1 = F(X1,N)
  NUM_F = NUM_F + 1
  IF (MWK(START(F1%MF)+2) == MUNKNO) THEN
    XMAX = X1
    FMAX = ABS(F1)
    SPIKE_FOUND = .TRUE.
    CALL FM_EXIT_USER_ROUTINE
    RETURN
  ELSE
    AVERAGE = AVERAGE + ABS(F1)
  ENDIF
ENDDO
AVERAGE = AVERAGE/99
```

```
! Search for a singularity in F.
```

```
DO
  X1 = XMAX + H
  IF (X1 > A + DX .AND. X1 < B - DX) THEN
    F1 = F(X1,N)
    NUM_F = NUM_F + 1
    IF (MWK(START(F1%MF)+2) == MUNKNO) THEN
      XMAX = X1
      FMAX = ABS(F1)
      SPIKE_FOUND = .TRUE.
      CALL FM_EXIT_USER_ROUTINE
      RETURN
    ENDIF
    IF (ABS(F1) > FMAX) THEN
```

```

        XMAX = X1
        FMAX = ABS(F1)
        H = -(H*14)/10
    ENDIF
ENDIF
H = -(H*10)/14
AB = MAX(ABS(A),ABS(B))
CALL FM_ULP(AB, EPS)
IF (ABS(H) < ABS(EPS)) THEN
    IF (FMAX > 50*AVERAGE) THEN
        SPIKE_FOUND = .TRUE.
        CALL FM_EXIT_USER_ROUTINE
        RETURN
    ELSE
        EXIT
    ENDIF
ENDIF
ENDDO

```

! Search for a singularity in F'.

```

FPMAX = -1
AVERAGE = 0
AB = MAX(ABS(A),ABS(B))
CALL FM_ULP(AB, EPS)
EPS = SQRT(EPS)
DO J = 1, 99
    X1 = A + (J*(B-A))/100
    IF (X1-EPS <= A) CYCLE
    F1 = F(X1-EPS, N)
    IF (X1+EPS >= B) CYCLE
    F2 = F(X1+EPS, N)
    NUM_F = NUM_F + 2
    IF (MWK(START(F1%MFM)+2) == MUNKNO .OR. MWK(START(F2%MFM)+2) == MUNKNO) THEN
        IF (MWK(START(F1%MFM)+2) == MUNKNO) THEN
            XMAX = X1 - EPS
            FMAX = ABS(F1)
        ELSE
            XMAX = X1 + EPS
            FMAX = ABS(F2)
        ENDIF
        SPIKE_FOUND = .TRUE.
        CALL FM_EXIT_USER_ROUTINE
        RETURN
    ELSE
        D = ABS((F2-F1)/(2*EPS))
        AVERAGE = AVERAGE + D
        IF (D > FPMAX) THEN
            XPMAX = X1
            FPMAX = D
        ENDIF
    ENDIF
ENDDO
AVERAGE = AVERAGE/99

H = MIN(XPMAX-A, B-XPMAX)/2

```

```

DO
  X1 = XPMAX + H
  IF (X1 > A + DX .AND. X1 < B - DX) THEN
    F1 = F(X1-EPS,N)
    NUM_F = NUM_F + 1
    IF (MWK(START(F1%MF)+2) == MUNKNO) THEN
      XPMAX = X1
      FPMAX = ABS(F1)
      SPIKE_FOUND = .TRUE.
      CALL FM_EXIT_USER_ROUTINE
      RETURN
    ENDIF
    F2 = F(X1+EPS,N)
    NUM_F = NUM_F + 1
    IF (MWK(START(F2%MF)+2) == MUNKNO) THEN
      XPMAX = X1+EPS
      FPMAX = ABS(F2)
      SPIKE_FOUND = .TRUE.
      CALL FM_EXIT_USER_ROUTINE
      RETURN
    ENDIF
    D = ABS((F2-F1)/(2*EPS))
    IF (D > FPMAX) THEN
      XPMAX = X1
      FPMAX = D
      H = -(H*14)/10
    ENDIF
  ENDIF
  H = -(H*10)/14
  AB = MAX(ABS(A),ABS(B))
  CALL FM_ULP(AB,T)
  IF (ABS(H) < ABS(T)) THEN
    IF (FPMAX > 50*AVERAGE) THEN
      SPIKE_FOUND = .TRUE.
      XMAX = XPMAX
      FMAX = FPMAX
      CALL FM_EXIT_USER_ROUTINE
      RETURN
    ELSE
      EXIT
    ENDIF
  ENDIF
ENDDO

CALL FM_EXIT_USER_ROUTINE
END SUBROUTINE FM_SPIKE

```